SIEMENS 4<sup>466</sup>



ACVATIX™

# Modulating control valve MXG462S.. with magnetic actuator, PN16

stainless steel

- Short positioning time (< 2 s), high-resolution stroke (1 : 1000)
- Selectable valve characteristic: equal-percentage or linear
- High rangeability
- Operating voltage AC / DC 24 V
- Selectable standard signal inputs DC 0/2...10 V or DC 0/4...20 mA
- DC 0...20 V Phs phase-cut signal input for Staefa controllers
- . Indication of operating state, visible from the outside
- Wear-free inductive stroke measurement
- Low friction, robust and maintenance-free
- Spring return facility:  $A \rightarrow AB$  closed when de-energized
- Positioning control, position feedback and manual control
- · Parts in contact with medium in CrNi steel

Use

The control valves MXG462S.. are mixing or through-port valves. They are supplied with the magnetic actuator ready fitted, equipped with an electronics module for position control and position feedback.

The short positioning time, high resolution and high rangeability make these valves ideal for modulating control of open and closed circuits with the highest control requirements.

Type reference	DN	Connection	k <sub>vs</sub>	$\Delta p_{\text{max}}$	Δps	Operating voltage	Positioning S		Spring return
		[inch]	[m <sup>3</sup> /h]	[kPa]	[kPa]		signal	time	function
MXG462S50-30	50	G 2¾B	30	600	600	AC 24 V DC 2030 V	DC 0/210 V or DC 0/420 mA	< 2 s	<b>✓</b>

DN = Nominal size

 $k_{vs}$  = Nominal flow rate of cold water (5 to 30 °C) through the fully opened valve (H<sub>100</sub>) at a differential pressure of 100 kPa (1 bar)

Δp<sub>max</sub> = Maximum permissible differential pressure across the valve's control path, valid for the entire actuating range of the motorized valve (mixing: path A-AB, B-AB)

 $\Delta p_{S}$  = Maximum permissible differential pressure at which the motorized valve will close securely against the pressure (close off pressure)

#### Accessories

Type reference	Description
Z366	Stem heating element for media temperatures < 0 °C, AC / DC 24 V, 10 W

#### **Ordering**

Valve body and magnetic actuator form one assembly and cannot be separated.

When placing an order, please specify the quantity, product description and type code.

#### Example:

Type reference	Stock number	Description	Quantity
MXG462S50-30	MXG462S50-30	Modulating control valve with magnetic actuator	2
Z366	Z366	Stem heating element	2

#### Delivery

A CrNi-Stahl seal disc with 3 gaskets is part of the delivery.

Union fittings must be supplied by the installer.

The Z366 stem heating is delivered in a separate package.

#### Rev. no.

Overview table, see page 11.

# Replacement electronics module

ASE12

Should the valve electronics prove faulty, the electronics module must be replaced by the ASE12 replacement electronics module. Mounting instruction no. 74 319 0404 0 is included.

#### Technical and mechanical design

For a detailed description of operation, refer to data sheet CA1N4028E.

#### **Control operation**

The electronics module converts the positioning signal to a phase-cut power signal which generates a magnetic field in the coil. This causes the armature to change its position in accordance with the interacting forces (magnetic field, counter spring, hydraulics). The armature responds rapidly to any change in signal, transferring the corresponding movement directly to the valve plug, enabling fast changes in load to be corrected quickly and accurately.

The valve's position is measured continuously (inductive). The internal positioning controller balances any disturbance in the system rapidly and delivers the position feedback signal. The valve stroke is proportional to the positioning signal.

#### Control

The magnetic actuator can be driven by a Siemens controller or a controller of other manufacture that deliver a Dc 0...10 V, DC 2...10 V, DC 0...20 mA or DC 4...20 mA output signal.

To achieve optimum control performance, it is recommended to use a 4-wire connection. In case of DC power supply, a 4-wire connection is **mandatory!** 

#### Spring return facility

If the positioning signal is interrupted, or in the event of a power failure, the valve's return spring will automatically close control path  $A \rightarrow AB$ 

#### **Manual control**

#### **MANUAL**

By pressing (a) and turning (b) the hand wheel in:

 clockwise (CW) direction, control path A → AB can be mechanically opened to between 80...90 %.

#### OFF

By pressing (a) and turning (b) the hand wheel in:

 counterclockwise (CCW) direction, the actuator will be switched off and the valve closed.

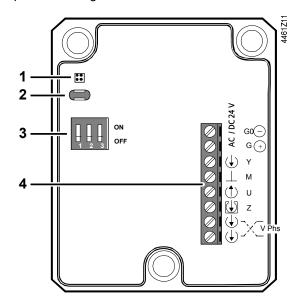
As soon as the hand wheel is pressed and turned, neither the forced control signal Z nor the input signal Y or the phase-cut signal acts on the actuator. The green LED will flash.

# b Auto b

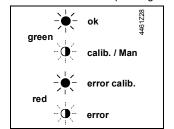
#### **AUTO**

For automatic control, the hand wheel must be set to the Auto position. The green LED will be lit.

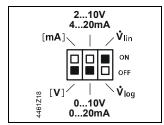
# Operator controls and indicators in the electronics housing



1 LED for indication of operating stat

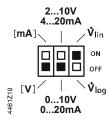


- 2 Opening for auto calibration
- 3 DIL switch for mode control



4 Connection terminals

# Configuration DIL switches

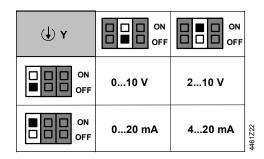


Switch	Function	ON / OFF	Description
1 %Z ON SQ OFF	Positioning signal Y	ON	[mA]
64 <b>■ □ □ □</b> OFF	T OSITIONING SIGNAL T	OFF	[V] <sup>1)</sup>
2 % ON	Positioning range	ON	210 V, 420 mA
⊕ OFF	Y and U	OFF	<b>010 V</b> , 020 mA <sup>1)</sup>
3 ON OFF	Valve characteristic	ON	V <sub>lin</sub> (linear) 1)
4461 OFF	valve characteristic	OFF	V <sub>log</sub> (equal-percentage)

1) Factory settings

# Selection positioning signal and range Y

Voltage and current



# Selection positioning range Y and U:

0...10 V / 0...20 mA or 2...10 V / 4...20 mA

(†) U	ON OFF	ON OFF	
Ri > 500 Ω	010 V	210 V	
Ri < 500 Ω	020 mA	420 mA	4461Z23

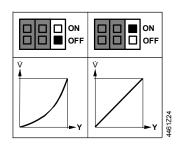
Output signal U (position feedback signal) is dependent on the load resistance Ri.

Ri > 500  $\Omega$ ,  $\rightarrow$  voltage signal

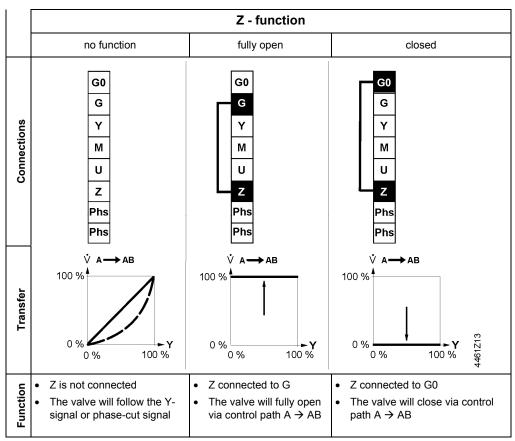
Ri < 500  $\Omega$ ,  $\rightarrow$  current signal

## Selection valve characteristics

Equal-percentage or linear



#### Forced control input Z



#### Signal priority

- 1. Hand wheel position Man (open) or Off
- 2. Forced control signal Z
- 3. Phase-cut signal
- 4. Signal input Y

#### Calibration

If the electronics module is replaced or the actuator turned through 180 °, the valve's electronics must be recalibrated. For that, the hand wheel must be set to Auto.

The printed circuit board has a slot (position 3, preceding page). Calibration is made by bridging the contacts located behind the slot using a screwdriver. The valve will then travel across the full stroke to store the end positions.



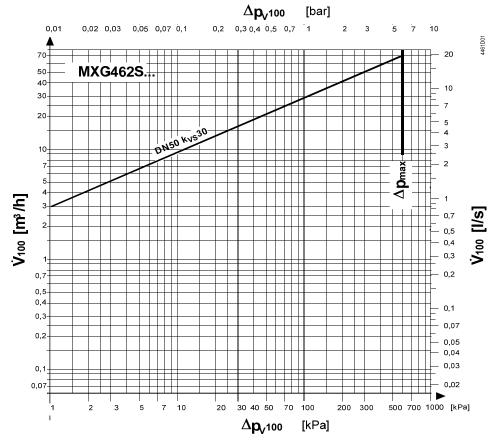
While calibration is in progress, the green LED will flash for about 10 seconds (also refer to «Indication of operating state»).

# Indication of operating state

LED	Indication		Function	Remarks, troubleshooting
Green	Lit		Control mode	Normal operation; everything o.k.
	Flashing	-)•	Calibration	Wait until calibration is finished (green or red LED will be lit)
			In manual control	Hand wheel in Man or Off position
Red	Lit		Calibration error	Recalibrate (bridge contacts behind the calibration
		<b>/</b>	Internal error	slot)
				Replace electronics module
	Flashing		Mains fault	Check mains network (outside the frequency or voltage range)
			DC Supply - / +	DC supply + / - connection rectify
Both	Dark	Ω	No power supply	Check mains network, check wiring
		0	Electronics faulty	Replace electronics module

#### **Sizing**

#### Flow chart



 $\Delta p_{v100}$  = differential pressure across the fully open valve and the valve's control path by a volumetric flow  $V_{100}$ 

 $\dot{V}_{100}$  = volumetric flow with valve fully open (H<sub>100</sub>)

Δp<sub>max</sub> = maximum permissible differential pressure across the valve's control path, valid for the entire actuating range of the motorized valve (mixing: path A-AB, B-AB)

100 kPa = 1 bar ≈ 10 mWC

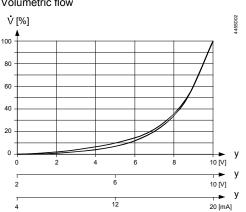
 $1 \text{ m}^3/\text{h} = 0.278 \text{ l/s water at } 20 ^{\circ}\text{C}$ 

#### Valve characteristic

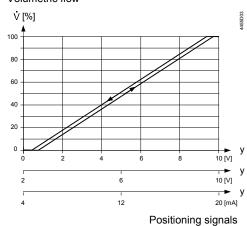
#### **Equal percentage**

#### Linear





Volumetric flow



#### Connection type 1)

The 4-wire connection should always be given preference!

Positioning signals

4-wire connection

	SNA	P <sub>MED</sub>	S <sub>TR</sub>	I <sub>F</sub>	wire cross-section [mm <sup>2</sup> ]		
	_				1,5	2,5	4,0
Type reference	[VA]	[W]	[VA]	[A]	max. cable length L [m]		
MXG462S	65	22	100	6.3	30	50	80

= nominal apparent power for selecting the transformer

 $P_{\text{med}} \\$ = typical power consumption

= Minimal require transformer power  $S_{TR}$ 

= required slow fuse  $I_{N}$ 

max. cable length; with 4-wire connections, the max. permissible length of the separate 1.5 mm<sup>2</sup> copper positioning signal wire is 200 m

#### **Engineering notes**

#### Attention 🛆

Conduct the electric connections in accordance with local regulations on electric installations as well as the internal or connection diagrams.

Safety regulations and restrictions designed to ensure the safety of people and property must be observed at all times!

In open circuits, there is a risk of valve disc seizing caused by scale deposits. Additionally, periodic actuation (twice or three times per week) must be planned.



With closed and open circuits always use a strainer upstream of the valve to increase the valve's functional safety.

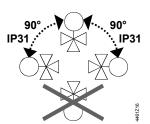
#### **Mounting notes**

The valve is supplied complete with Mounting Instruction no. 74 319 0378 0.

Caution 🛆

The valve may only be used as a mixing or through port valve, not as a diverting valve. Observe the direction of flow  $A \rightarrow AB$ !

#### Orientation



Degree of protection valid only when M20 cable gland supplied by the installer.

<sup>1)</sup> All information at AC 24 V

# When used as a through port valve

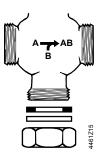
Only three-way MXG462S.. valves are supplied. They may be used as straight-through valves by closing off port «B».

Threaded valves MXG462S.. as throughport valves

Close off port B with a union fitting.

A Cr-Ni-Stahl seal disc with 3 gaskets is part of the delivery.

Union fittings conforming to ISO 49 / DIN 2950 must be supplied by the installer.



#### Installation notes

- The MXG462S.. valves are flat-faced allowing sealing with the gaskets provided.
- Do not use hemp for sealing the valve body threads.
- The actuator may not be lagged.







• For electrical installation, refer to «Connection diagrams», page 9.

#### **Maintenance notes**

The valves are maintenance-free.

The low friction and robust design make regular servicing unnecessary and ensure a long service life. The valve stem is sealed from external influences by a maintenance-free gland.

If the red LED is lit, the electronics must be recalibrated or replaced.

Repair

Should the valve electronics prove faulty, the electronics module must be replaced by the ASE12 replacement electronics module (refer to Mounting Instruction no 74 319 0404 0).



Always disconnect power before fitting or removing the electronics module.

After replacing the electronics module, calibration must be triggered in order to optimally match the electronics to the valve (refer to «Calibration », page 5)



The actuator must not be disposed of together with domestic waste. This applies in particular to the PCB.

Legislation may demand special handling of certain components, or it may be sensible from an ecological point of view.

Current local legislation must be observed.

#### Warranty

Application-specific technical data must be observed.

If specified limits are not observed, Siemens Switzerland Ltd / HVAC Products will not assume any responsibility.

Functional actuator	data					
Power supply		Extra low-voltage only (SELV, PE	LV)			
A	C 24 V	Operating voltage	AC 24 V +20 / –15 %			
		Frequency		4565 Hz		
		Typical power consumption	$P_{MED}$	22 W		
			Stand by	< 1 W (valve closed)		
		Apparent power S <sub>A</sub>		65 VA		
		Minimum power of transformer S <sub>T</sub>	R	100 VA		
		Required fuse I <sub>F</sub>		6.3 A, slow		
D	C 24 V	Operating voltage		DC 2030 V		
		Current draw at DC 24 V		0.5 A / 4 A (max.)		
Input		Positioning signal Y		DC 0/210 V or DC 0/420 mA		
•		or Phase Cut s	ignal Phs	020 V		
			0/210 V	100 kΩ // 5nF		
		•	420 mA	240 Ω // 5nF		
		Forced control Z				
		Impedance		22 kΩ		
		Close valve (Z connected to G	0)	< AC 1 V; < DC 0.8 V		
		Open valve (Z connected to G	-	> AC 6 V; > DC 5 V		
		No function (Z not wired)	,	phase-cut- or positioning signal Y active		
Output		Position feedback signal U	Voltage			
		3	_	DC 0/420 mA; load resistance $\leq$ 500 $\Omega$		
		Stroke measurement		Inductive		
		Nonlinearity		± 3 % of end value		
Positioning time		Positioning time		< 2 s		
Electrical connections		Cable entry point		2 x Ø 20.5 mm (for M20)		
		Connecting terminal		terminal for 4 mm <sup>2</sup> wire		
		Min. wire cross-section		0.75 mm <sup>2</sup>		
		Max. cable length		refer to «connection type», page 5		
Functional valve data	a	PN class	DN 16 a	s per EN 1333		
Turictional valve data	u	41		1.6 MPa (16 bar)		
		Differential pressure Δpmax / Δps		table «Type summary», page 2		
		Valve characteristic <sup>2)</sup>		ercentage or linear, n <sub>d</sub> = 3 as per		
		valve characteristic		DE 2173, optimized near the closing point		
				Data Sheet N4023)		
		Leakage rate at	,	< 0.05 % of k <sub>vs</sub> value		
		$\Delta p = 0.1 \text{ MPa } (1 \text{ bar})$		< 0.2 % k <sub>vs</sub> depending on operation		
		$\Delta p = 0.1$ Wil a (1 bal)		conditions		
		Permissible media	chilled (	cold and hot water, water with anti-freeze;		
		T CITIISSIDIC ITICUIA		endation: water treatment as per VDI 2035		
		Medium temperature 3)	-20130	•		
		Stroke resolution $\Delta H / H_{100}$		(H = stroke)		
		Mode of operation	modulat	·		
		·				
		Hysteresis  Regition when do energized	typical 3			
		Position when de-energized	A → AB			
		Mounting position		to horizontal (observe safety standard)		
Matarials		Mode of operation	modulat			
Materials		Valve body, Covering flange		el (1.4581)		
		Seat, inner valve, plug	CrNi ste			
		Entire inner suit	CrNi ste			
		Valve stem seal	EPDM (	· · · · · · · · · · · · · · · · · · ·		
Dimensions / weight		Dimensions / weight	refer to «Dimensions», page 11			
		Threaded connection	as per ISO 228-1			
8/12						

#### Norms and standards

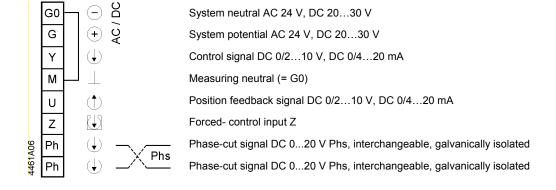
CE conformity					
CE-conformity to EMV-requirements	2004/108/FC				
•					
Immunity	EN 61000-6-2:[2005] Industrial 4)				
Emissions	EN 61000-6-3:[2007] Residential 4)				
Protection class	Class III as per EN 60730				
Emissions	Class 2 as per EN 60730				
Housing protection					
upright to horizontal	IP31 as per EN 60529				
Vibration <sup>5)</sup>	IEC 68-2-6				
	(1 g acceleration, 1100 Hz, 10 min)				
Conforming to UL	UL 873				
CSA	C22.2 No. 24				
C-tick	N 474				
Environmental compatibility	ISO 14001 (Environment)				
	ISO 9001 (Quality)				
	SN 36350 (Environmentally compatible products)				
	RL 2002/95/EC (RoHS)				
Pressure Equipment Directive	PED 97/23/EC				
Pressure accessories	as per article 1, paragraph 2.1.4				
Fluid group 2	without CE-marking as per article 3, section 3				
	(sound engineering practice)				

<sup>1)</sup> Tested at 1.5 x PN (24 bar), similar to DIN 3230-3.

## General environmental conditions

	Operation	Transport	Storage
	EN 60721-3-3	EN 60721-3-2	EN 60721-3-1
Climatic conditions	Class 3K5	Class 2K3	Class 1K3
Temperature	−5+45 °C	−25+70 °C	−5+45 °C
Humidity	595 % r.h.	595 % r.h.	595 % r.h.
Mechanical conditions	EN 60721-3-6		
	Class 6M2		

#### **Connection terminals**



<sup>&</sup>lt;sup>2)</sup> Can be selected via DIL switch.

 $<sup>^{3)}</sup>$   $\,$  Medium temperatures < 0  $^{\circ}\text{C},$  the Z366 stem heating element is required.

<sup>&</sup>lt;sup>4)</sup> Transformer 160 VA (e.g. Siemens 4AM 3842-4TN00-0EA0).

<sup>&</sup>lt;sup>5)</sup> In case of strong vibrations, use high-flex stranded wires for safety reasons.

#### Caution 🗥

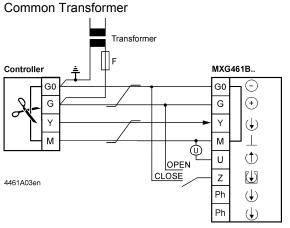
If controller and valve receive their power from separate sources, only one transformer may be earthed on the secondary side.

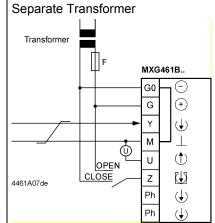
#### Caution 🛆

In case of DC power supply, a 4-wire connection is mandatory!

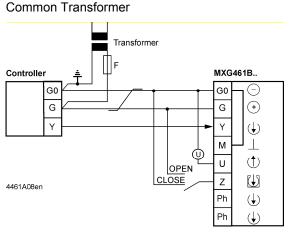
Terminal assignment for controller with 4-wire connection (to be preferred!). DC 0...10 V

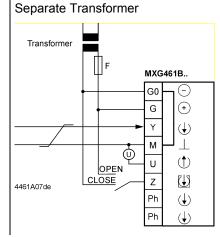
DC 2...10 V DC 0...20 mA DC 4...20 mA





Terminal assignment for controller with 3-wire connection DC 0...10 V DC 2...10 V DC 0...20 mA DC 4...20 mA



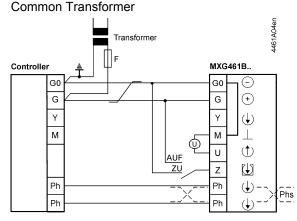


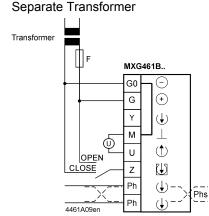
Indication of valve position (only if required). DC 0  $\dot{...}$ 10 V  $\rightarrow$  0...100 % volumetric flow V<sub>100</sub> Twisted pairs. If the lines for AC 24 V power supply and the DC 0...10 V (DC 2...10 V, DC 4... 20 mA) positioning signal are routed separately, the AC 24 V line need not be twisted.

#### Warning

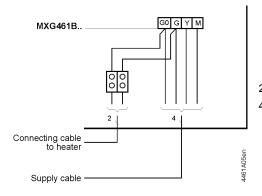
#### Piping must be connected to potential earth!

**Controllers with** phase-cut DC 0...20 V Phs





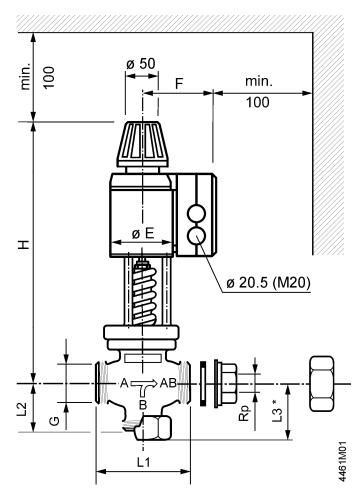
# Stem heating element Z366



- 2 AC/DC 24 V power supply for heating element
  - Power supply, positioning signals

#### **Dimensions**

#### Dimensions in mm



Type reference	DN	G	Rp	L1	L2	L3 *	Н	Е	F	kg 1)
-		[Inch]	[Inch]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]
MXG462S50-30	50	G 2¾B	Rp 2	170	93,5	108	402	100	125	18,6

- Externally thread G...B as per ISO 228-1
- Internally thread Rp... as per ISO 7-1
- Union fittings as per ISO 49 / DIN 2950
- \* When used as through port valve
- G Weight in kg (incl. packaging)

#### **Revision numbers**

Type reference	Valid from rev. No.
MXG462S50-30	A